

Inside the Rust Borrow Checker

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#lang-talk meetup

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Borrow Checker Rules

- Move
- Lifetime subset relation
- Borrow must outlive borrowee
- One mutable borrow or multiple immutable borrows
- No modification of immutable borrow data



Borrow Checker Rules

- Move

```
let mut v1 = Vec::new();  
v1.push(42)  
let mut v2 = v1; // <- Move  
println!(v1[0]); // <- Error
```

- Lifetime subset relation
- Borrow must outlive borrowee
- One mutable borrow or multiple immutable borrows
- No modification of immutable borrow data



Borrow Checker Rules

- Move
- Lifetime subset relation
- Borrow must outlive borrowee

```
fn f() -> &i32 {  
    &(1+1)  
} // <- Error
```

- One mutable borrow or multiple immutable borrows
- No modification of immutable borrow data



Borrow Checker Rules

- Move
- Lifetime subset relation
- Borrow must outlive borrowee
- One mutable borrow or multiple immutable borrows
- No modification of immutable borrow data

```
let mut counter = 0;  
let ref1 = &mut counter;  
// ...  
let ref2 = &mut counter; // <- Error
```



Checking Functions

```
struct Vec<'a> { ... }
```

```
impl<'a> Vec<'a> {  
    fn push<'b> where 'b: 'a (&mut self, x: &'b i32) {  
        // ...  
    }  
}
```



Checking Functions

```
struct Vec<'a> { ... }
```

```
impl<'a> Vec<'a> {  
    fn push<'b> where 'b: 'a (&mut self, x: &'b i32) {  
        // ...  
    }  
}
```

```
let a = 5;           // 'a    'b    'b: 'a  
{                   //  
    let mut v = Vec::new(); // *  
    v.push(&a);         // *    *    OK  
    let x = v[0];      // *    *    OK  
}                     // *    *    OK
```



Borrow checker evolution

Lexical, NLL, Polonius



Lexical borrow checker

```
fn foo() {  
    let mut data = vec!['a', 'b', 'c'];  
    capitalize(&mut data[..]);  
    data.push('d');  
    data.push('e');  
    data.push('f');  
}
```



Lexical borrow checker

```
fn foo() {  
    let mut data = vec!['a', 'b', 'c']; // --+ 'scope  
    capitalize(&mut data[..]);         // |  
    // ^~~~~~ 'lifetime // |  
    data.push('d');                     // |  
    data.push('e');                     // |  
    data.push('f');                     // |  
} // <-----+
```



Lexical borrow checker

```
fn bar() {  
    let mut data = vec!['a', 'b', 'c'];  
    let slice = &mut data[..]; // <-+ 'lifetime  
    capitalize(slice);        // |  
    data.push('d'); // ERROR! // |  
    data.push('e'); // ERROR! // |  
    data.push('f'); // ERROR! // |  
} // <-----+
```



Lexical borrow checker

```
fn process_or_default() {  
    let mut map = ...;  
    let key = ...;  
    match map.get_mut(&key) { // -----+ 'lifetime  
        Some(value) => process(value), // |  
        None => { // |  
            map.insert(key, V::default()); // |  
            // ^~~~~~ ERROR. // |  
        } // |  
    }; // <-----+  
}
```



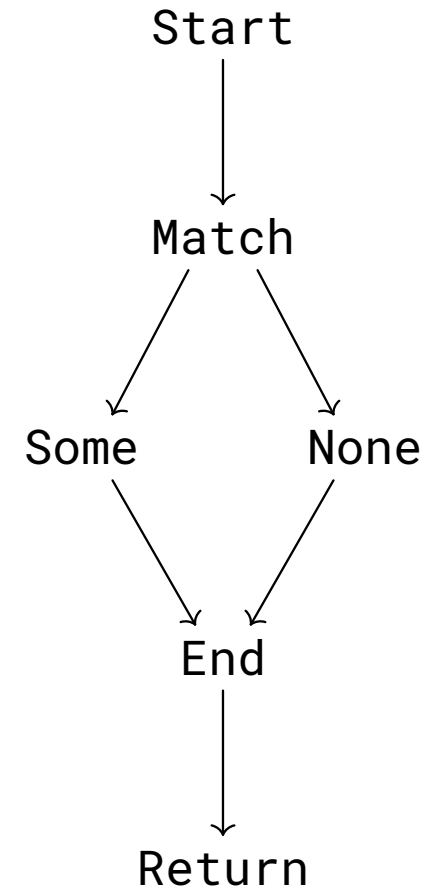
Non-lexical lifetimes (NLL)

lifetime = set of CFG nodes



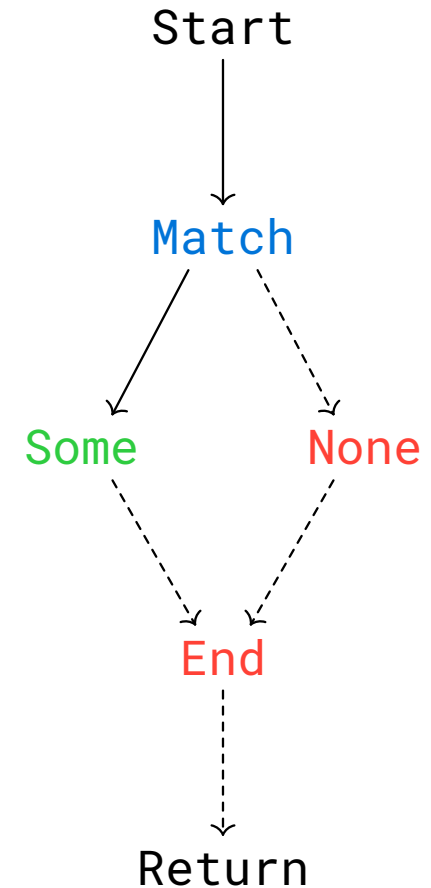
Non-lexical lifetimes (NLL)

```
fn f<'a>(map: &'r mut HashMap<K, V>) {  
    ...  
    match map.get_mut(&key) {  
        Some(value) => process(value),  
        None => {  
            map.insert(key, V::default());  
        }  
    }  
}
```



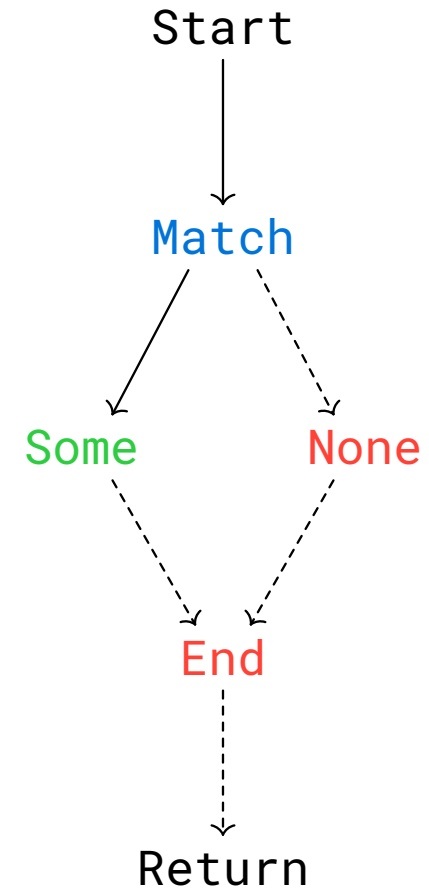
Non-lexical lifetimes (NLL)

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    match map.get_mut(&key) {  
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        None => {  
            map.insert(key, V::default());  
        }  
    }  
}
```



Non-lexical lifetimes (NLL)

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fn f<'a>(map: &'r mut HashMap<K, V>) {  
    ...  
    match map.get_mut(&key) {  
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        }  
    }  
}
```

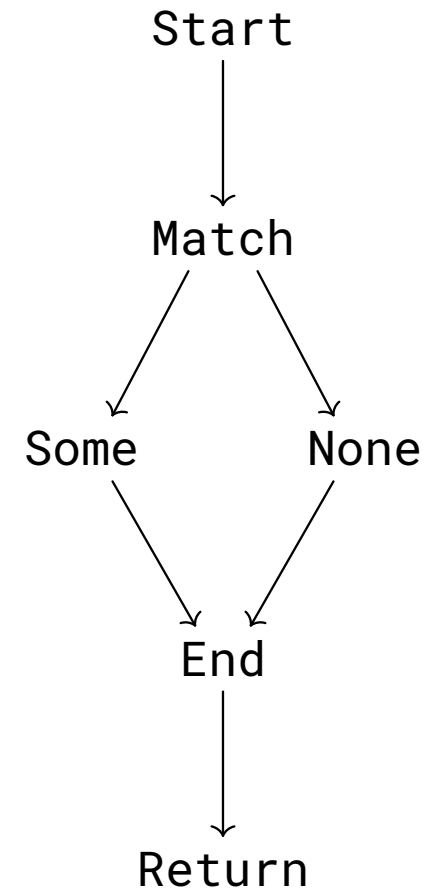


NLL → lifetimes are CFG nodes



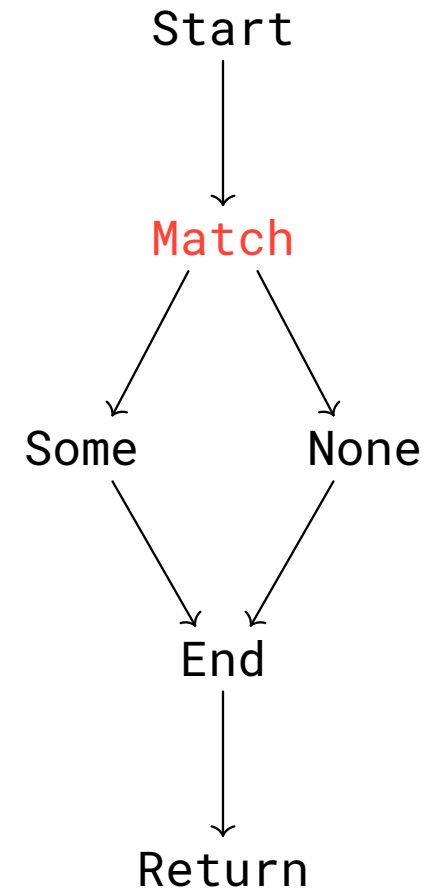
Breaking NLL

```
fn f<'a>(map: &'a mut Map<K, V>) -> &'a
V {
  ...
  match map.get_mut(&key) {
    Some(value) => process(value),
    None => {
      map.insert(key, V::default())
    }
  }
}
```



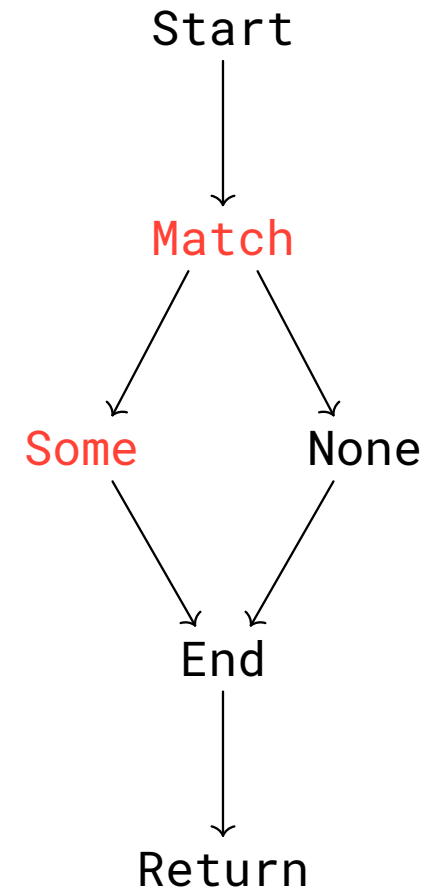
Breaking NLL

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fn f<'a>(map: &'a mut Map<K, V>) -> &'a
V {
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      map.insert(key, V::default())
    }
  }
}
```



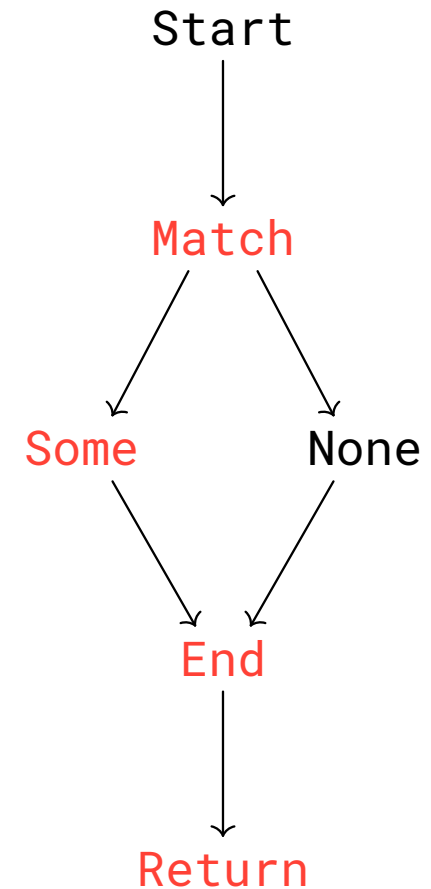
Breaking NLL

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V {
  ...
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    None => {
      map.insert(key, V::default())
    }
  }
}
```



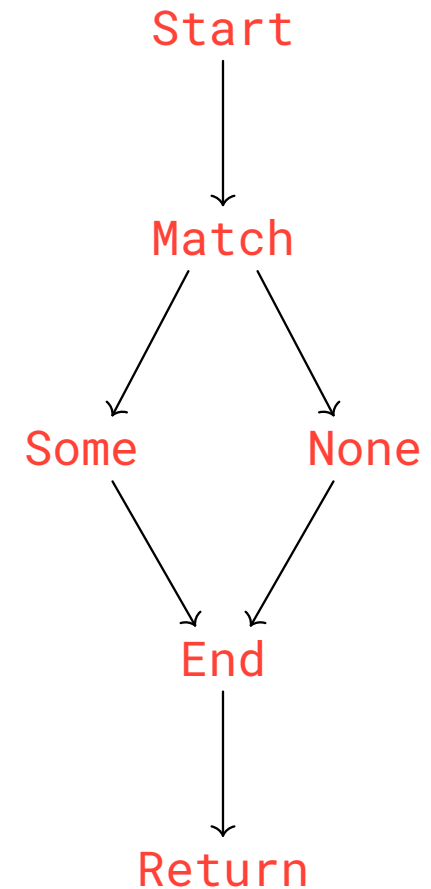
Breaking NLL

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    }
  }
}
```



Breaking NLL

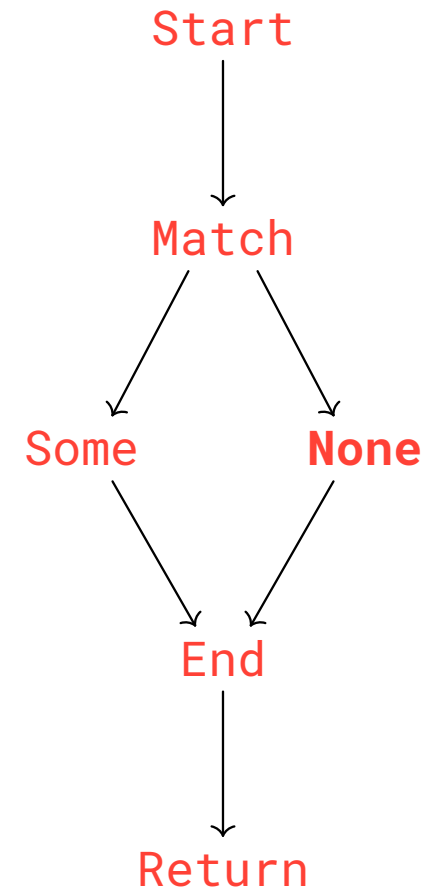
```
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V {
  ...
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    None => {
      map.insert(key, V::default())
    }
  }
}
```



Breaking NLL

```
fn f<'a>(map: &'a mut Map<K, V>) -> &'a
V {
  ...
  match map.get_mut(&key) {
    Some(value) => process(value),
    None => {
      map.insert(key, V::default())
    }
  }
}
```

Error!



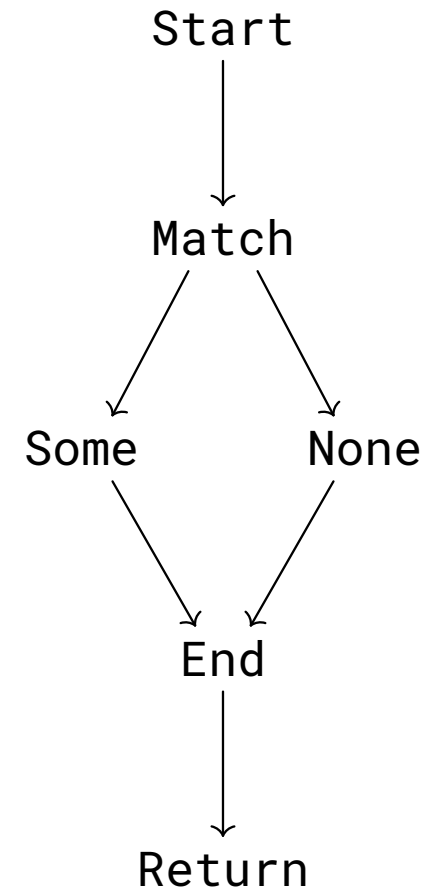
Polonius

Lifetime = set of loans



Polonius

```
fn f<'a>(map: Map<K, V>) -> &'a V {  
    ...  
    match map.get_mut(&key) {  
        Some(value) => process(value),  
        None => {  
            map.insert(key, V::default());  
        }  
    }  
}
```



Polonius

```
let r: &'0 i32 = if (cond) {  
    &x /* Loan L0 */  
} else {  
    &y /* Loan L1 */  
};
```



How does the program look?

Internal representations



Internal representations

- AST = abstract syntax tree
- HIR = high-level IR
- Ty = type IR
- THIR = typed HIR
- **MIR** = mid-level IR

```
struct Foo(i31);
```

```
fn foo(x: i31) -> Foo {  
    Foo(x)  
}
```



HIR

```
Fn {
  generics: Generics { ... },
  sig: FnSig {
    header: FnHeader { ... },
    decl: FnDecl {
      inputs: [
        Param {
          ty: Ty {
            Path { segments: [ PathSegment {
              ident: i32#0 } ] }
          }
          pat: Pat { Ident(x#0) }
        },
      ],
      output: Ty { Path { segments: [ PathSegment {
        ident: Foo#0 } ] }
    }
  }
}
```



MIR

```
fn foo(_1: i32) -> Foo {  
    debug x => _1;  
    let mut _0: Foo;  
  
    bb0: {  
        _0 = Foo(_1);  
        return;  
    }  
}
```



MIR: Fibonacci

```
fn fib(_2: u32) -> u32 {
  bb0: {
    0   StorageLive(_3);
    1   StorageLive(_5);
    2   _5 = _2;
    3   StorageLive(_6);
    4   _6 = Operator(move _5, const u32);
    5   switchInt(move _6) -> [bb1, bb2];
  }

  bb1: {
    0   _3 = const bool;
    1   goto -> bb3;
  }

  bb2: {
    0   StorageLive(_8);
    1   _8 = _2;
    2   StorageLive(_9);
    3   _9 = Operator(move _8, const u32);
    4   _3 = move _9;
    5   goto -> bb3;
  }

  bb3: {
    0   switchInt(move _3) -> [bb4, bb5];
  }

  bb4: {
    0   _1 = const u32;
    1   goto -> bb8;
  }

  bb5: {
    0   StorageLive(_14);
    1   _14 = _2;
    2   StorageLive(_15);
    3   _15 = Operator(move _14, const u32);
    4   StorageLive(_16);
    5   _16 = Call(fib)(move _15) -> [bb6];
  }

  bb6: {
    1   _19 = _2;
    3   _20 = Operator(move _19, const u32);
    5   _21 = Call(fib)(move _20) -> [bb7];
  }

  bb7: {
    0   _1 = Operator(move _16, move _21);
    7   goto -> bb8;
  }

  bb8: {
    5   return;
  }
}
```

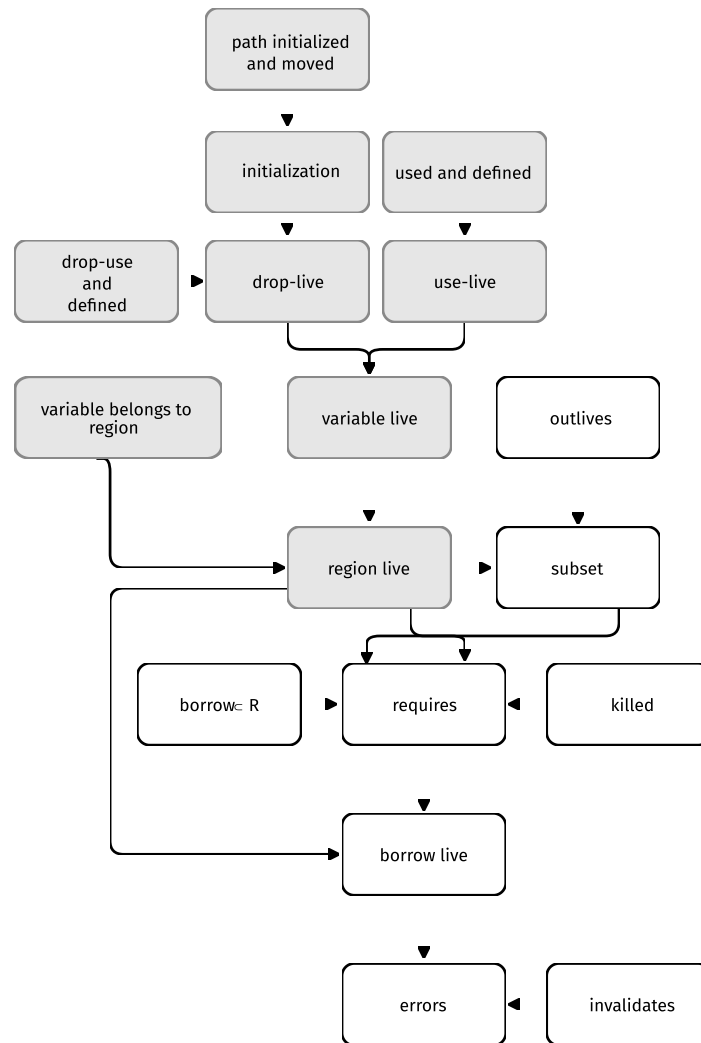


Computing!

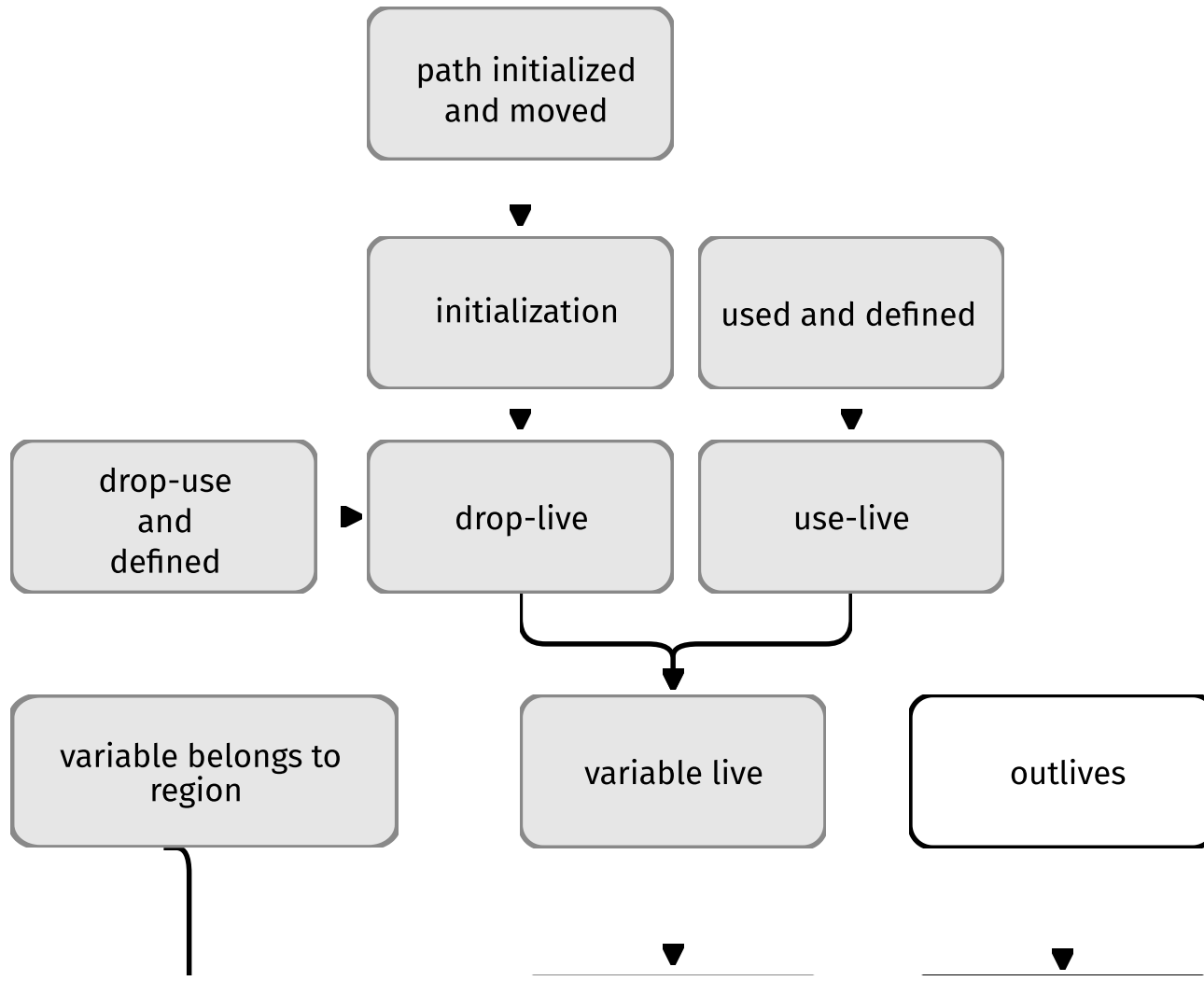
Steps of the borrow checker



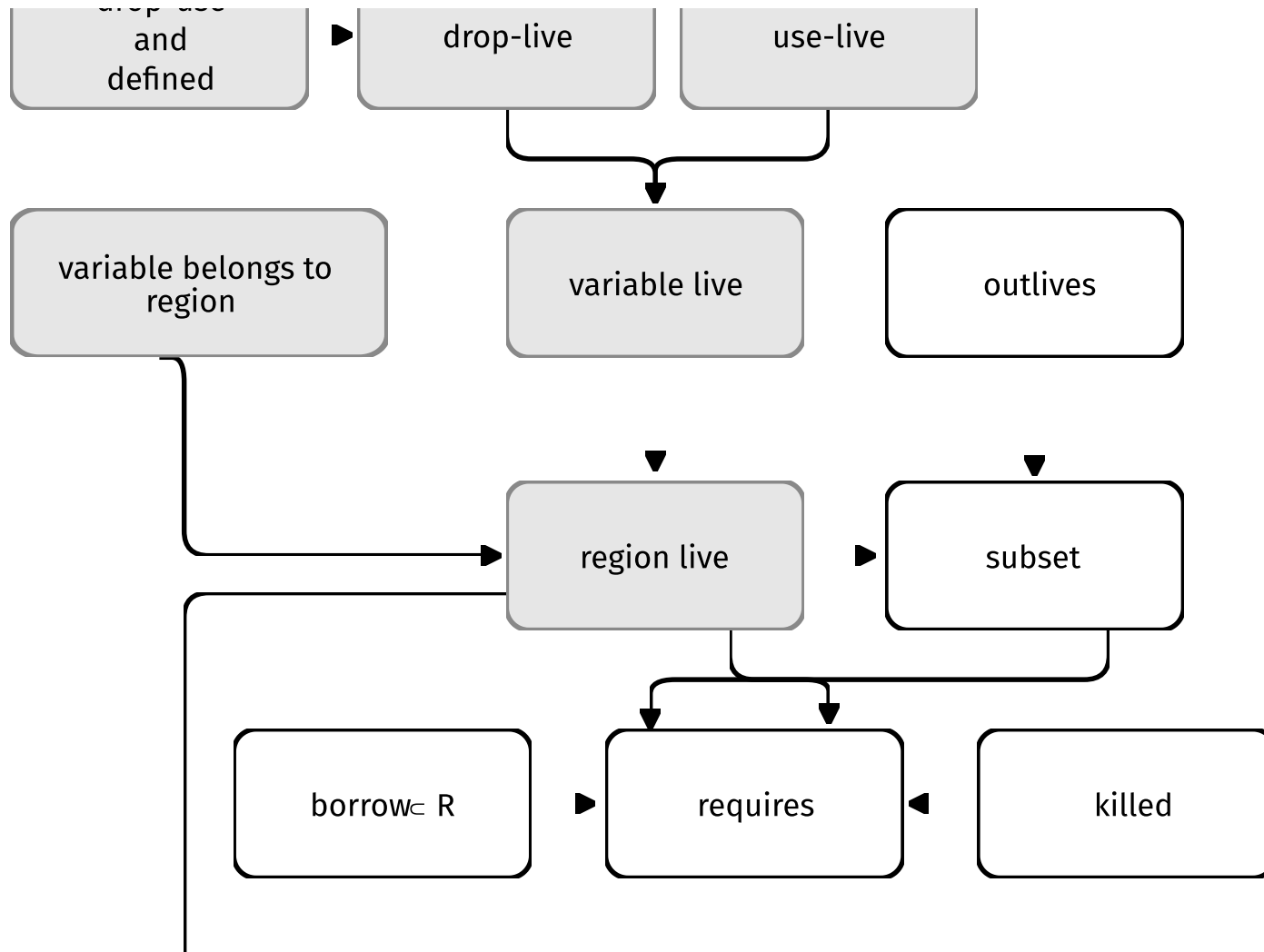
What do we need?



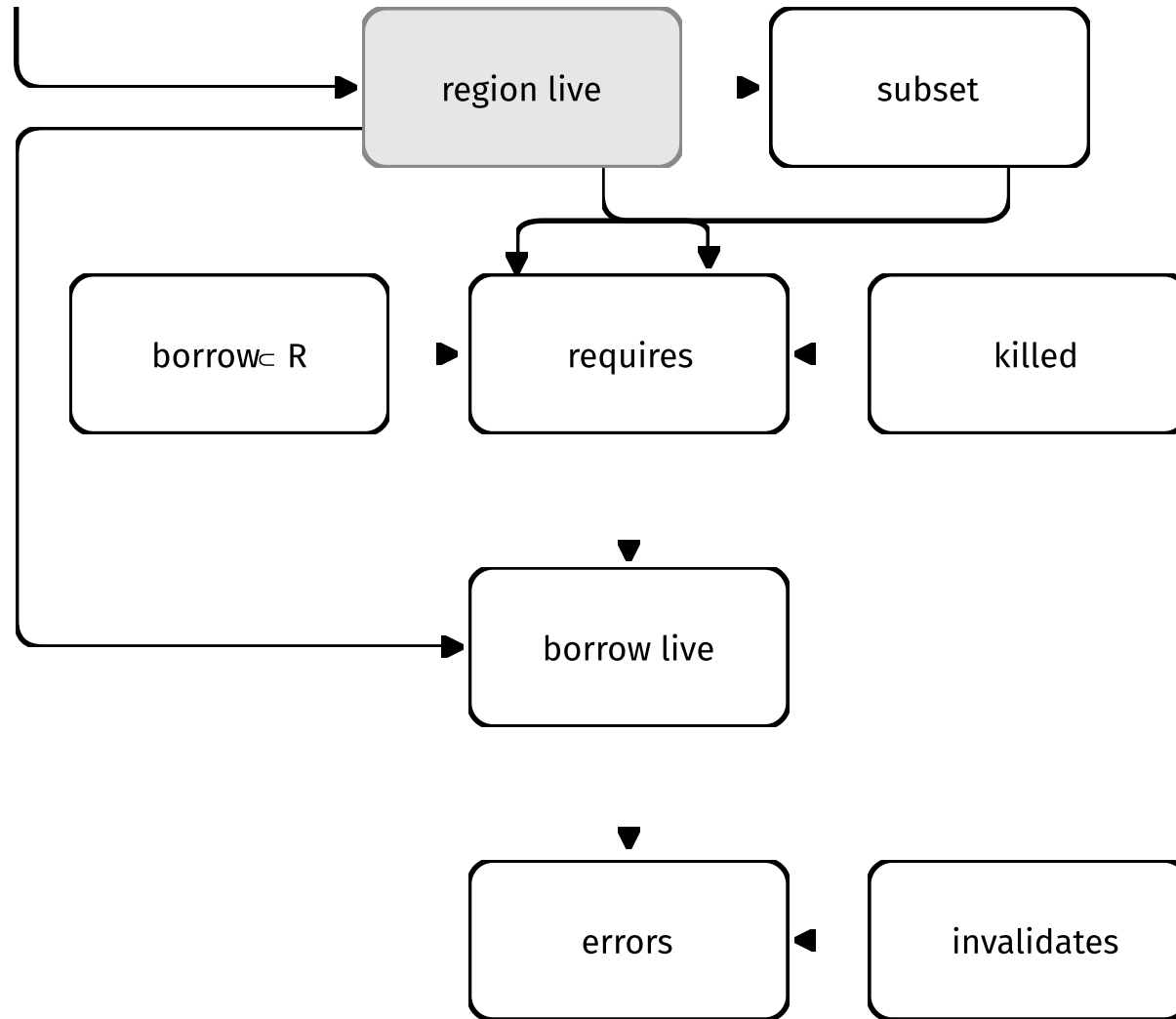
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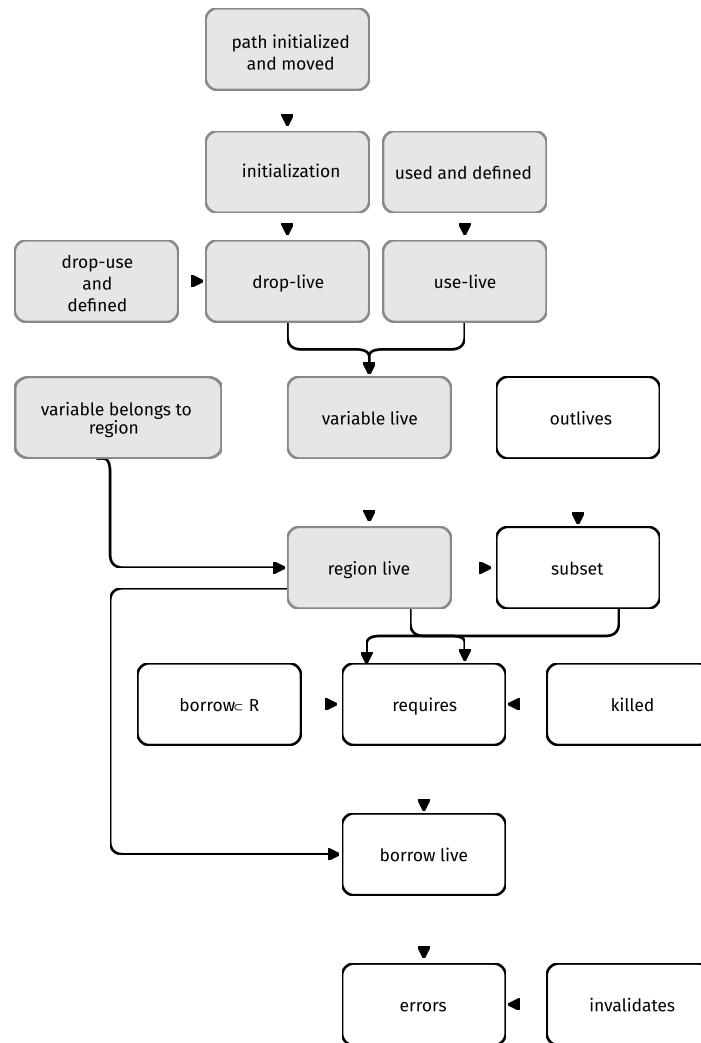
What do we need?



What do we need?



What do we need?



What about lifetime annotations?

```
let x: &'a i32;
```



Lifetime annotations everywhere

```
fn max_ref(a: &i32, b: &i32) -> &i32 {  
    let mut max = a;  
    if (*max < *b) {  
        max = b;  
    }  
    max  
}
```



Lifetime annotations everywhere

```
fn max_ref(a: &'a i32, b: &'a i32) -> &'a i32 {  
    let mut max = a;  
    if (*max < *b) {  
        max = b;  
    }  
    max  
}
```



Lifetime annotations everywhere

```
fn max_ref(a: &'a i32, b: &'b i32) -> &'c i32 {  
    let mut max = a;  
    if (*max < *b) {  
        max = b;  
    }  
    max  
}
```



Lifetime annotations everywhere

```
fn max_ref(a: &'a i32, b: &'b i32) -> &'c i32 {  
    let mut max: &i32 = a;  
    if (*max < *b) {  
        max = b;  
    }  
    max  
}
```

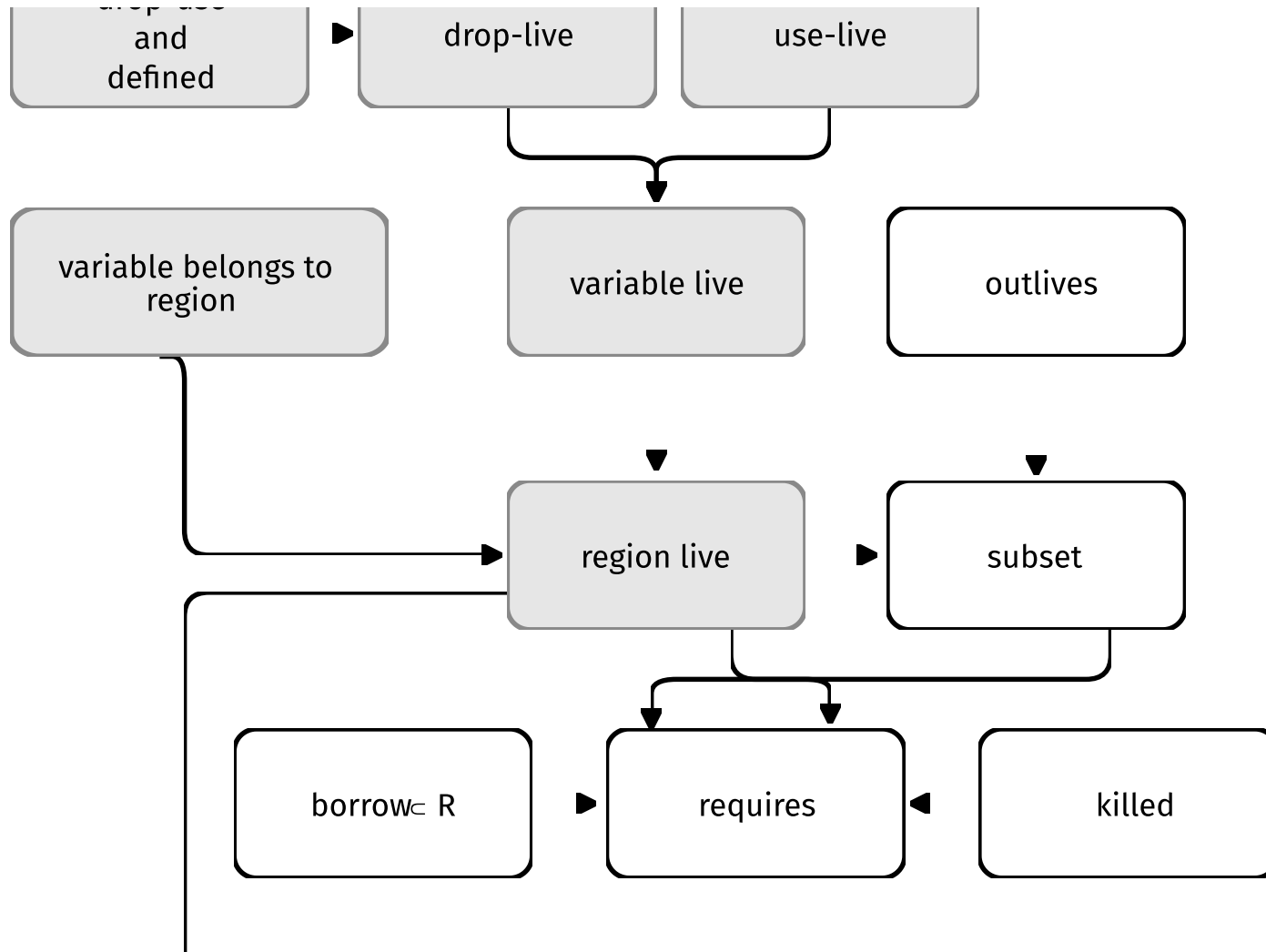


Lifetime annotations everywhere

```
fn max_ref(a: &'a i32, b: &'b i32) -> &'c i32 {  
    let mut max: &'?1 i32 = a;  
    if (*max < *b) {  
        max = b;  
    }  
    max  
}
```

```
max = a      'a: '?1  
max = b      'b: '?1  
return max   '?1: 'c
```





Is it that simple?

```
Customer<'&a, Vec<(Box<dyn Dealer>, &'b mut i32)>>
```

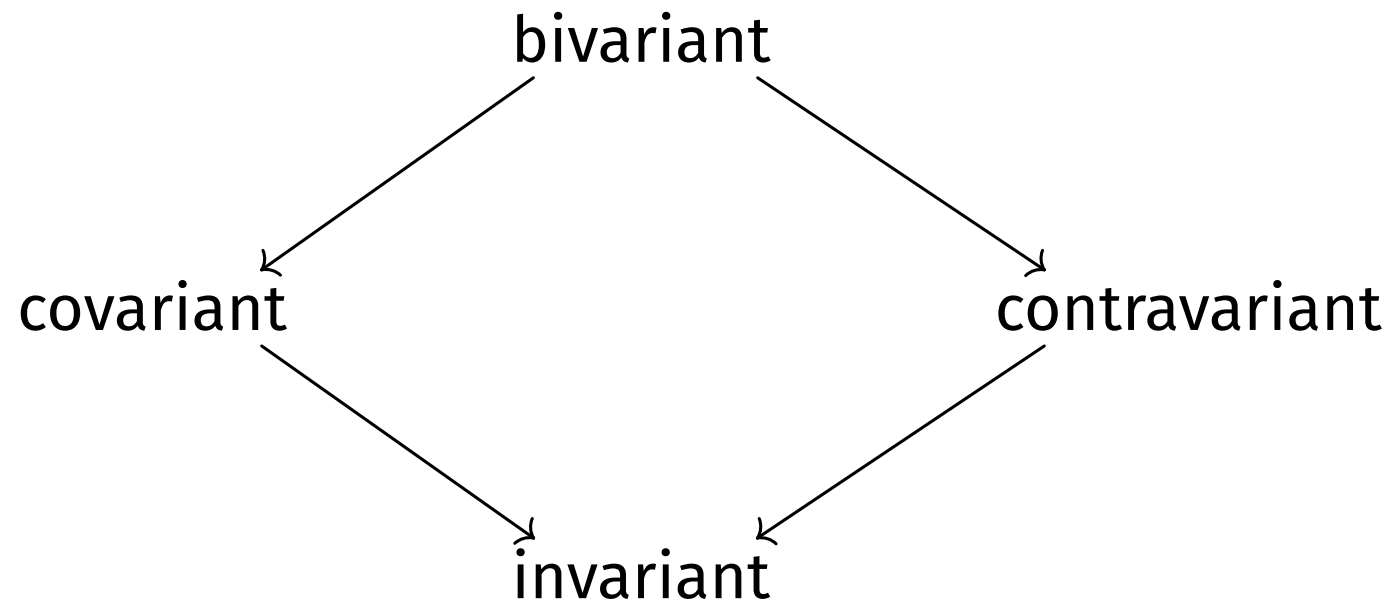


Variance

```
struct T<'a> {  
    a: &'a i32,  
    f: fn(&'a i32),  
}
```

$$T\langle'a\rangle \subseteq T\langle'b\rangle$$
$$'a \langle ? \rangle 'b$$


Variance



Example: Variance Computation

```
struct Foo<'a, 'b, T> {  
    x: &'a T,  
    y: Bar<T>,  
}
```

- **Collect variance info**

- $f_0 = 0, f_1 = 0, f_2 = 0$
- x in the covariant position:
 - $\&'a T$ in the covariant position: $f_0 = +$ and $f_2 = +$
- y in the covariant position:
 - $f_2 = \text{join}(f_2, \text{transform}(+, b_0))$



Example: Variance Computation

```
struct Foo<'a, 'b, T> {  
    x: &'a T,  
    y: Bar<T>,  
}
```

- **Iteration 1:**

- $f_0 = +, f_1 = o, f_2 = +.$
- $\text{transform}(+, b_0) = -$
- $\text{join}(*, -) = *$



Example: Variance Computation

```
struct Foo<'a, 'b, T> {  
    x: &'a T,  
    y: Bar<T>,  
}
```

- **Iteration 2:**

- $f_0 = +, f_1 = o, f_2 = *$.
- $\text{transform}(+, b_0) = -$
- $\text{join}(*, -) = *$



Example: Variance Computation

```
struct Foo<'a, 'b, T> {  
    x: &'a T,  
    y: Bar<T>,  
}
```

- Final variances: $f_0 = +$, $f_1 = 0$, $f_2 = *$:
 - f_0 is evident.
 - f_1 remains bivariant, as it is not mentioned in the type.
 - f_2 is invariant due to its usage in both covariant and contravariant positions.



Why is it useful?

```
fn main() {  
    let s = String::new();  
    let x: &'static str = "hello world";  
    let mut y = &*s;  
    y = x;  
}
```



Example: Variance in rustc

```
fn write_scope_tree(
    tcx: TyCtxt<'_>,
    body: &Body<'_>,
    scope_tree: &FxHashMap<...>,
    w: &mut dyn io::Write,
    parent: SourceScope,
    depth: usize,
) -> io::Result<()> { ... }
```



Example: Variance in rustc

```
fn write_scope_tree(
    tcx: TyCtxt<'_>,
    body: &Body<'_>,
    scope_tree: &FxHashMap<...>,
    w: &mut dyn io::Write,
    parent: SourceScope,
    depth: usize,
) -> io::Result<()> { ... }

if let ty::Adt(_, _) = local_decl.ty.kind() {
    display_adt(tcx, &mut indented_decl, local_decl.ty);
}

pub fn display_adt<'tcx>(tcx: TyCtxt<'tcx>, w: &mut
String, ty: Ty<'tcx>) {...}
```



Example: Variance in rustc

```
fn write_scope_tree<'a>(
    tcx: TyCtxt<'a>,
    body: &Body<'a>,
    scope_tree: &FxHashMap<...>,
    w: &mut dyn io::Write,
    parent: SourceScope,
    depth: usize,
) -> io::Result<()> { ... }
```



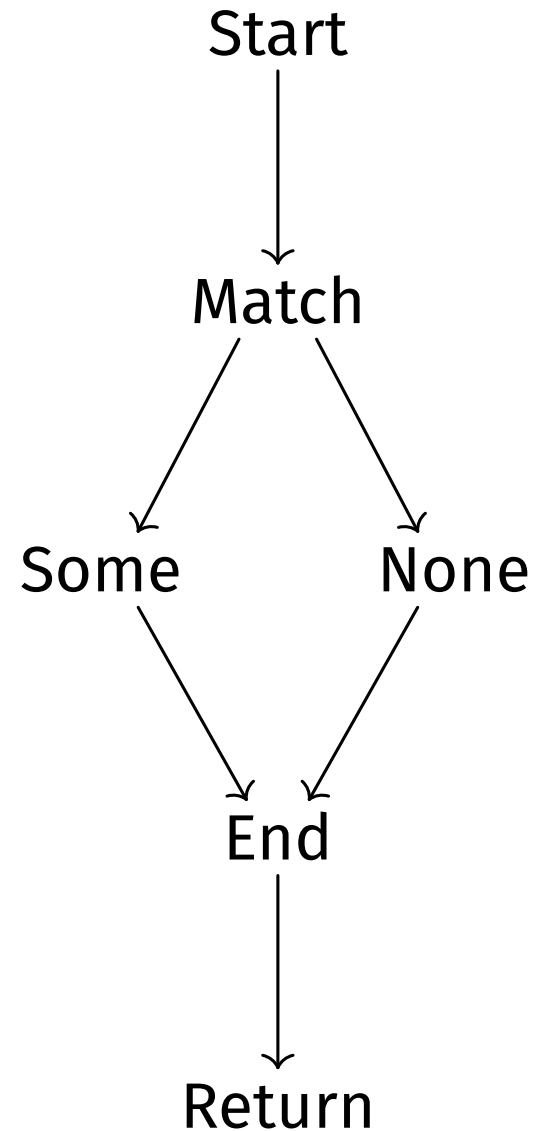
But how?

Dataflow, datalog, Polonius



Dataflow

- Semilattice
- State
 - IN
 - OUT
- Transform function
- Iteration



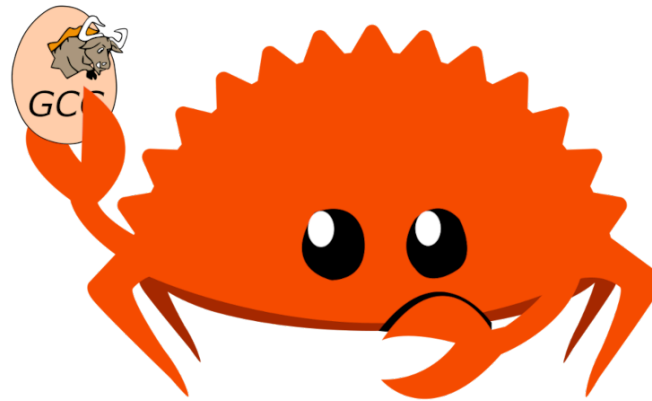
Datalog Polonius

```
origin_contains_loan_on_entry(Origin, Loan, Point) :-  
    loan_issued_at(Origin, Loan, Point).
```

```
origin_contains_loan_on_entry(Origin2, Loan, Point) :-  
    origin_contains_loan_on_entry(Origin1, Loan, Point),  
    subset(Origin1, Origin2, Point).
```

```
origin_contains_loan_on_entry(Origin, Loan, TargetPoint) :-  
    origin_contains_loan_on_entry(Origin, Loan, SourcePoint),  
    !loan_killed_at(Loan, SourcePoint),  
    cfg_edge(SourcePoint, TargetPoint),  
    (origin_live_on_entry(Origin, TargetPoint);  
placeholder(Origin, _)).
```

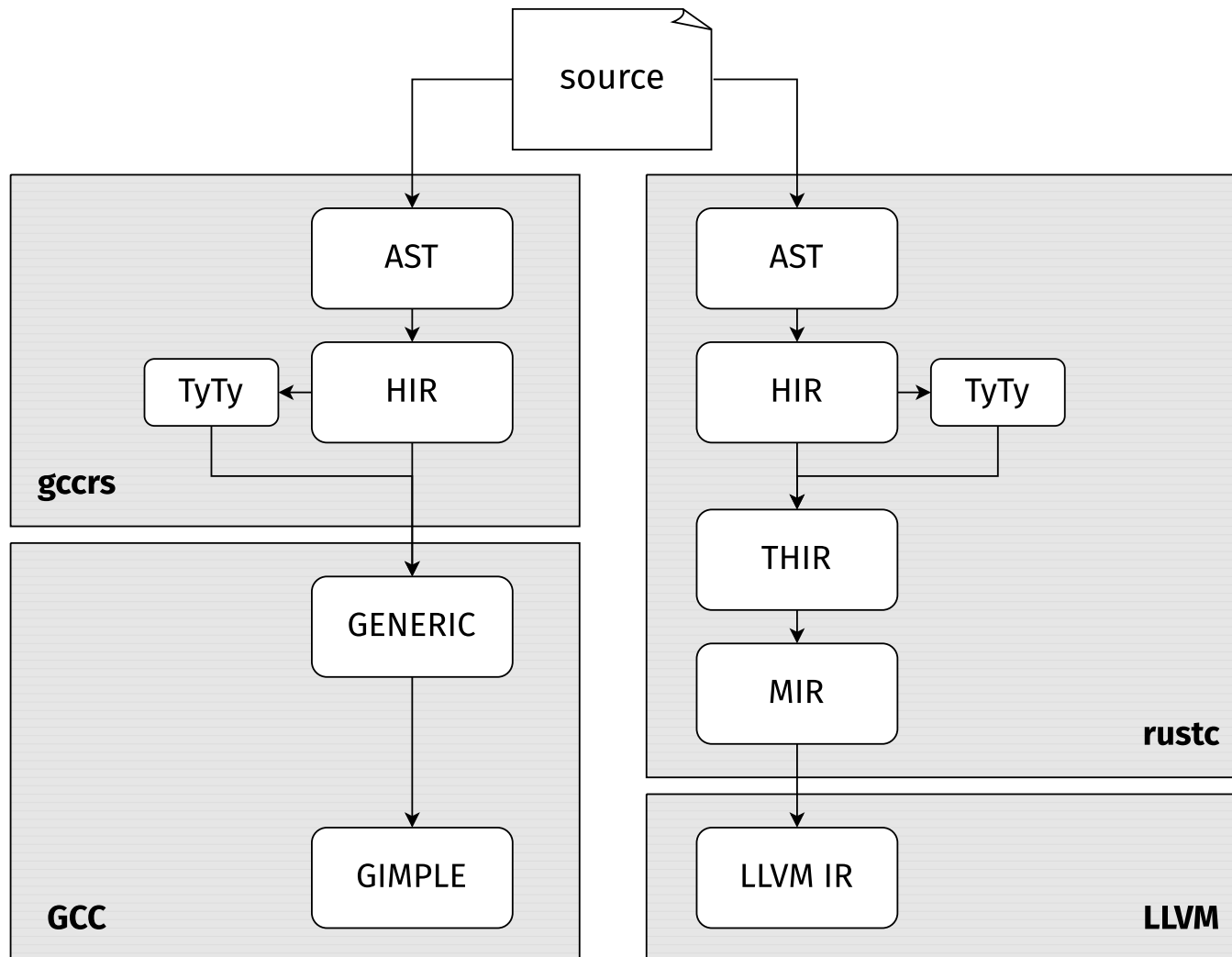




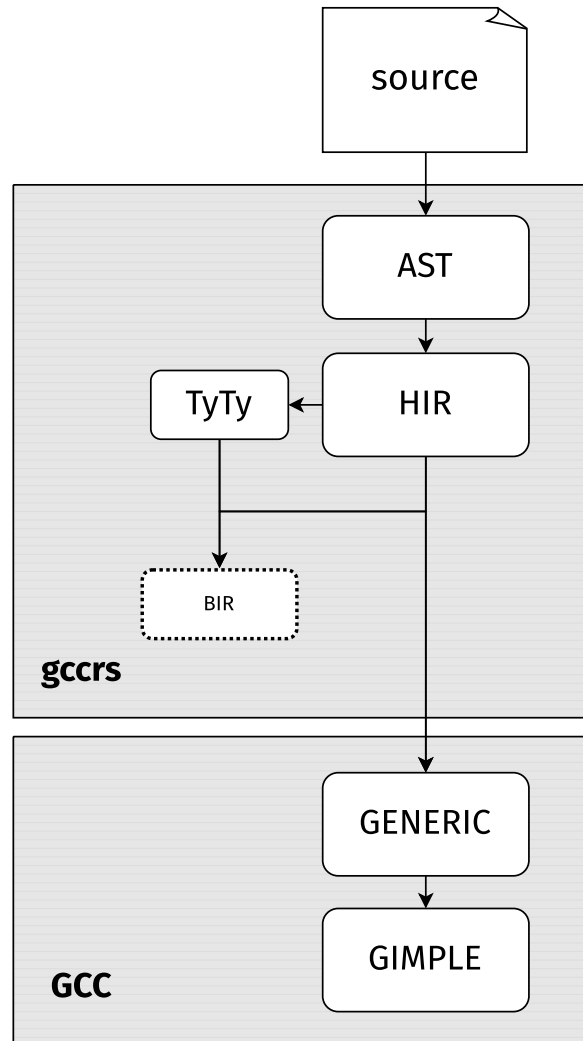
Bonus: Rust GCC



Rust GCC



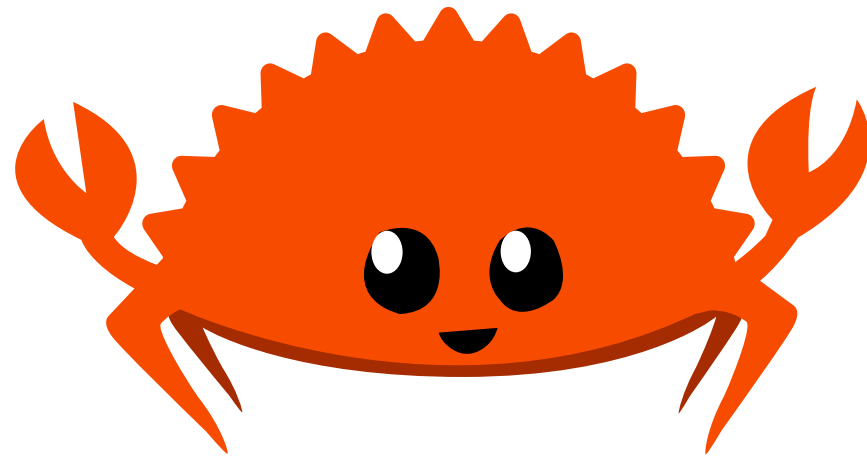
Rust GCC



References

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That's all Folks!

